## Python-series SCARA Robot

# Python550F-B6

With superior speed, accuracy, linearity, and verticality performance, it can quickly and precisely complete tasks such as gluing, assembly, transfer, and packaging.

#### Applicable industries

Transportation and loading/unloading, dispensing, gluing, assembly and inspection processes in electronics, food, medicine, daily chemicals, and semiconductors.

#### Product features

Rated load	3kg	
Max. load	6kg	
Number of axes	4	
Installation type	Hoisting	

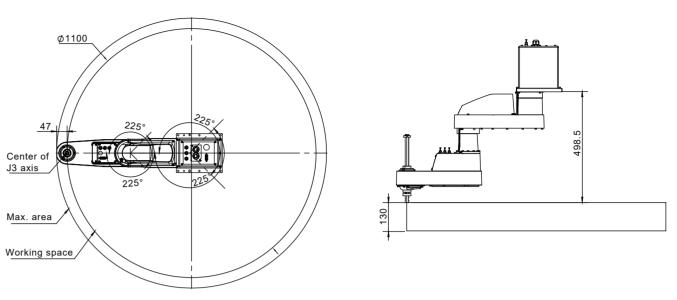


- p		,		
	Robotic arms 1 & 2	550	0mm	
Robotic arm length	Robotic arm 1	275	5mm	
	Robotic arm 2	275	5mm	
Max. operating speed	Joints 1 & 2	740	00mm/s	
	Joint 3	110	00mm/s	
	Joint 4	260	00°/s	
Repeat positioning accuracy	Joints 1 & 2	±0.	02mm	
	Joint 3	±0.	01mm	
	Joint 4	±0.	01°	
Joint 4 allowable inertial torque	Rated	0.0	05kg·m²	
	Max.	0.0	J5kg⋅m²	
	Joint 1	±22	25°	
NA/a daina a mana a a	Joint 2	±22	25°	
Working range	Joint 3	130	0mm	
	Joint 4	±72	20°	
	0.1kg	1		
25/305/25	3kg	0.5	is	
	6kg	0.5	72s	
Power supply voltage		Sin	Single-phase AC 220 V-240 V, 50/60 Hz	
Rated power			KW	
Ambient temperature			5°C	
Relative humidity			95%	
Degree of protection			54	
Installation aperture		190	0x160mm; 6-φ6.5	
Electrical interface		10-	-channel custom I/O	
Airway		φ4'	*3	
Weight		20	kg (excluding cables and racks)	
I/O interface		8-ch	nannel configurable digital I/O nannel universal digital I/O (8 additional I/O channels can be added) nannel encoder input	
Ethernet		1		
USB		2		
RS232\RS485		1		
Communication protocol		Mo	dbus-RTU/TCP、Socket	

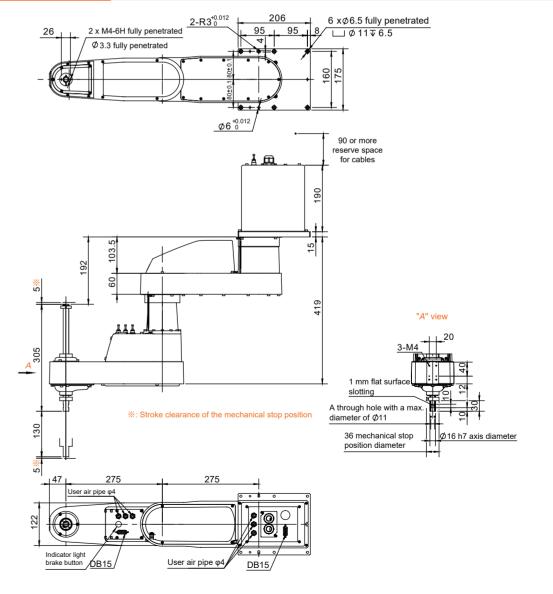
<sup>\*:</sup> For specific requirements regarding line selection, interface configuration, and other optional needs, please consult the technicians of RobotPhoenix.

### Working range (unit: mm)





## Installation size (unit: mm)



<sup>\*:</sup> Any changes resulting from upgrading our products will not be notified separately.